

On the quasi-stationary expansion in gravity

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2106.13268

1703.03459
1903.10682
2002.02688
2210.15440

work in progress

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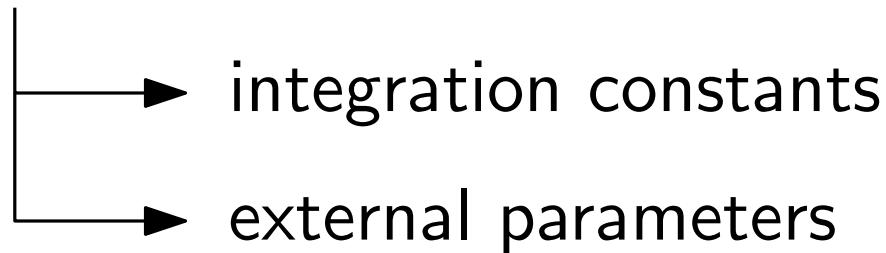
A. Beyen, E. Hamamcı,
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Slow ~~Food~~ Physics

quasi-stationary/adiabatic/Manton/moduli space/... approximation

1) Starting point: $\bar{f}(x; z)$ family of (time-independent) solutions

z : parameters labelling different solutions

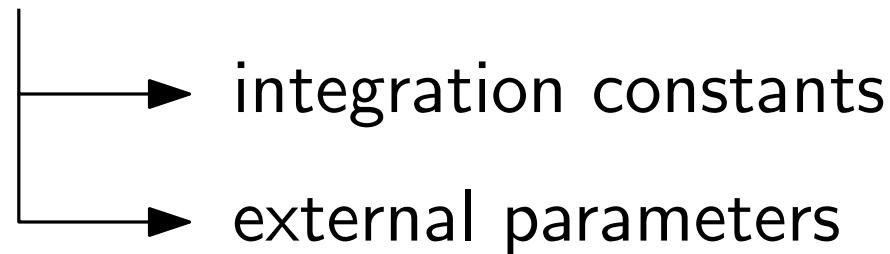


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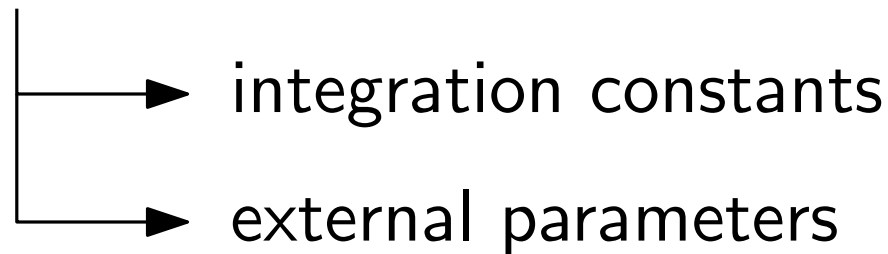
2) Ansatz: $f(x, t) = \bar{f}(x; z(t))$

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1) Starting point: $\bar{f}(x; z)$ family of (time-independent) solutions

z : parameters labelling different solutions



2) Ansatz: $f(x, t) = \bar{f}(x; z(t)) + \mathcal{O}(\dot{z})$

3) Insert into equations and solve perturbatively in small \dot{z} .

Motion on the space of vacua

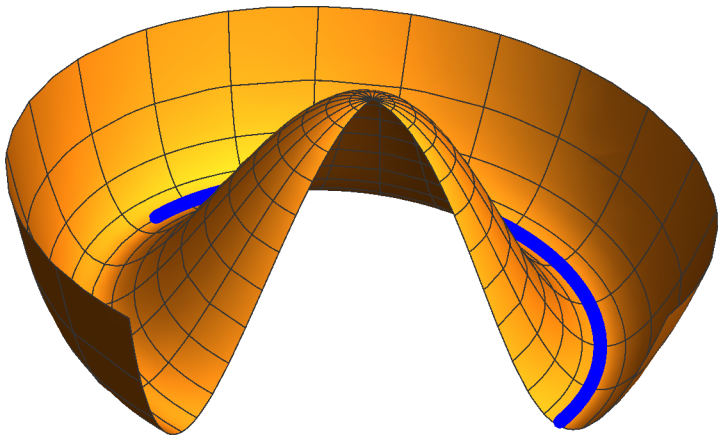
- Vacuum: minimal energy equilibrium configuration
 \Leftrightarrow absolute minimum of potential
- Focus on case with manifold of vacua = 'space of vacua' \mathcal{V}
 \hookrightarrow typical for theories with symmetry breaking: $\mathcal{V} = \mathcal{S}/\mathcal{K}$
- Kinetic Energy defines a metric on configuration space \mathcal{C}
 $\mathcal{V} \subset \mathcal{C} \Rightarrow$ induced metric on \mathcal{V}
- For small velocities **free motion on \mathcal{V}** [corrections $\mathcal{O}(v^2)$]
 \hookrightarrow geodesic motion

Motion on the space of vacua

Example I

$$L = \frac{1}{2}g(\dot{x}, \dot{x}) - V(x) = \frac{m}{2}\dot{x}^a\dot{x}^a - (R^2 - x^a x^a)^2$$

Mexican Hat potential



$$\mathcal{C} = \mathbb{R}^n$$

$$\mathcal{V} = S^{n-1} = \frac{\text{SO}(n)}{\text{SO}(n-1)}$$

centrifugal force $\sim \frac{v^2}{R}$

restoring force $\sim R^2(R - r)$

$$\Rightarrow (R - r) \sim \frac{v^2}{R^3}$$

Motion on the space of vacua

Example II

$$L = \frac{\eta_{\mu\nu} \dot{x}^\mu \dot{x}^\nu}{2N} - N \frac{(R^2 - \eta_{\mu\nu} x^\mu x^\nu)^2}{2}$$

↑ reparametrization invariant

Gaugefix $N = 1$

$$L = \frac{\eta_{\mu\nu} \dot{x}^\mu \dot{x}^\nu}{2} - \frac{(R^2 - \eta_{\mu\nu} x^\mu x^\nu)^2}{2}$$

$$\mathcal{C} = \mathbb{R}^{n+1}$$

$$\mathcal{V} = \text{dS}_n = \frac{\text{SO}(1, n)}{\text{SO}(1, n-1)}$$

↑ Lorentzian signature

Motion on the space of vacua

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constraint

$$-\eta_{\mu\nu} \dot{x}^\mu \dot{x}^\nu = (\eta_{\mu\nu} x^\nu x^\mu - R^2)^2$$

on \mathcal{V}

↓
null geodesic motion

Motion on the space of vacua

GR (on $\mathbb{R} \times M$)

In synchronous gauge/Gaussian normal coordinates

$$(ds^2 = dt^2 + h_{ij}(x, t) dx^i dx^j)$$

$$L = \frac{1}{2} g(\dot{h}, \dot{h}) - V(h)$$

$$g(\delta_1 h, \delta_2 h) = \frac{1}{2} \int_M d^3 x \sqrt{h} h^{i[k} h^{j]l} \delta_1 h_{ij} \delta_2 h_{kl} \quad (\text{WdW})$$

$$V(h) = -\frac{1}{2} \int_M d^3 x \sqrt{h} R(h)$$

\mathcal{C} = space of all Riemannian metrics on M (superspace)

↑ highly singular

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$$L = \frac{1}{2}g(\dot{h}, \dot{h}) - V(h)$$

+ constraints !
(momentum and Hamiltonian)

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What is \mathcal{V} ?

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What is \mathcal{V} ?

$$\text{Ric}(h) = 0 \stackrel{d=3}{\Leftrightarrow} \text{Riem}(h) = 0 \Leftrightarrow h_{ij} = \delta_{ij} \text{ up to diffeo}$$

$$\mathcal{G} = \{\phi \in \text{Diff}(M) \mid \phi(\partial M) = \partial M\}$$

$$\mathcal{G}_0 = \{\phi \in \text{Diff}(M) \mid \phi|_{\partial M} = \text{id}\} \quad \leftarrow \begin{array}{l} \text{gauge} \\ \text{symmetry} \end{array}$$

$$\mathcal{S} = \mathcal{G}_0 \setminus \mathcal{G} = \text{Diff}(\partial M) \quad \leftarrow \text{global symmetry}$$

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$$\mathcal{V} = \mathcal{S}/\mathcal{K} = \text{Diff}(\partial M)/\text{ISO}(\partial M) = \mathcal{G}_0 \setminus \mathcal{G} / \text{Stab}(h^o)$$

\uparrow non-trivial only when $\partial M \neq \emptyset$
 \leftarrow perfectly smooth (but ∞ -dimensional)

Motion on the space of vacua

Previous slide somewhat axiomatic, physical derivation of \mathcal{V} ?

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e.g. by small velocity approximation

bonus:

- induced metric on \mathcal{V}
- Einstein equations as geodesic motion on \mathcal{V}
- infinite number of conserved boundary charges

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setup:

$\bar{h}_{ij}^o(x)$ a reference flat metric

ϕ_z a spatial diffeo (z coordinate on $\text{Diff}(M)$)

\Rightarrow generic flat metric $\bar{h}_{ij}(x; z) = \phi_z \cdot \bar{h}_{ij}^o(x)$

Restrict time dependence to $h_{ij}(x, t) = \bar{h}_{ij}(x; z(t))$

determine $z(t)$ in the limit of small \dot{z}

Motion on the space of vacua

$$h_{ij}(x, t) = \bar{h}_{ij}(x; z(t)) \quad \Rightarrow \quad \dot{h}_{ij} = \bar{\nabla}_{(i} \chi_{j)}^z$$

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- Momentum constraint: $\nabla^i \partial_{[i} \chi_{j]}^z = 0$

Fixes χ up to boundary value ζ (and an exact part)

$$\hookrightarrow \in \mathfrak{diff}(M) / \mathfrak{diff}_0(M) = \mathfrak{diff}(\partial M)$$

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$$\Rightarrow L = \frac{1}{2} \bar{g}_z(\dot{z}, \dot{z}) \quad \bar{g}_z(\dot{z}, \dot{z}) = \langle \zeta_z, \zeta_z \rangle_{\bar{h}(z)}$$

$$\langle \zeta_{(1)}, \zeta_{(2)} \rangle_h \equiv \oint_{\partial M} \sqrt{k} d^2 y \left(\zeta_{(1)}^a D^\perp \zeta_{(2)}^a - K_{ab} \zeta_{(1)}^a \zeta_{(2)}^b \right)$$

\bar{g} pseudo-Riemannian metric on $\text{Diff}(\partial M) / \text{ISO}(\partial M)$

Motion on the space of vacua

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\bar{g} pseudo-Riemannian metric on $\text{Diff}(\partial M)/\text{ISO}(\partial M)$

- Hamiltonian constraint:

imposes \dot{z} to be null wrt \bar{g}
determines exact part of χ

- Dynamic Einstein equation \Leftrightarrow geodesic equation for \bar{g}



**AND NOW FOR SOMETHING
COMPLETELY DIFFERENT.**

The $1/c$ expansion of GR

covariant non-relativistic (small v !) expansion (Dautcourt)

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covariant non-relativistic (small v !) expansion (Dautcourt)

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Ansatz: $g_{\mu\nu}^{(-2)} = -\tau_{\mu}\tau_{\nu}$ (natural via $x^0 = ct$)

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- It follows that

$$\begin{aligned} g^{\mu\nu(0)} &= h^{\mu\nu} \\ \Gamma_{\mu\nu}^{\lambda(0)} &= \Gamma_{\mu\nu}^{\lambda(nc)} \end{aligned} \quad (\text{assuming } \Gamma_{\mu\nu}^{\lambda(-2)} = 0)$$

$(\tau_{\mu}, h^{\mu\nu})$ with $\tau_{\mu}h^{\mu\nu} = 0$ forms a Newton-Cartan structure

The $1/c$ expansion of GR

covariant non-relativistic (small v !) expansion (Dautcourt)

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- and that

Newton-Cartan gravity

$$R_{\mu\nu}^{(0)} = 8\pi G_N \tilde{T}_{\mu\nu}^{(0)} \Leftrightarrow R_{\mu\nu}^{(\text{nc})} = 4\pi G_N \rho \tau_{\mu}\tau_{\nu}$$

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turns out to be
weak gravity
assumption

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relax this
assumption

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- One finds extension of NC ($d\tau = 0 \rightarrow \tau \wedge d\tau = 0$)

Torsional connection

$$\Gamma_{\mu\nu}^{(\text{nc})\lambda} - \Gamma_{\nu\mu}^{(\text{nc})\lambda} = T_{\mu\nu}^{\lambda} \neq 0$$

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Physical interpretation

extends Newtonian gravity with time-dilation effects

The $1/c$ expansion of GR

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Bonus: expansion consistent at level of the action

(Hansen, Hartong, Obers)

The $1/c$ expansion of GR

3+1 formulation of the $1/c$ expansion

$$ds^2 = -e^\psi (c dt + C_i dx^i)^2 + e^{-\psi} \gamma_{ij} dx^i dx^j$$

$g_{\mu\nu} \Leftrightarrow (\psi, C_i, \gamma_{ij})$ Kol-Smolkin decomposition
(dual to ADM decomposition)

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$$L = L_0 + c^{-1} L_1 + c^{-2} L_2$$

$$L_0 = R + \frac{1}{4} e^{2\psi} C_{ij} C^{ij} - \frac{1}{2} \partial_i \psi \partial^i \psi,$$

$$L_1 = \Gamma^{ij kl} D_i C_j \dot{\gamma}_{kl} + (2\partial^j \psi - e^{2\psi} C^{ij} C_i) \dot{C}_j + C^i \partial_i \psi \dot{\psi},$$

$$\begin{aligned} L_2 = & -\Gamma^{ij kl} C_i \dot{C}_j \dot{\gamma}_{kl} + e^{-2\psi} \dot{\gamma} \dot{\psi} - 2C^i \dot{C}_i \dot{\psi} \\ & + \frac{1}{4} (e^{-2\psi} \Gamma^{kl mn} + \Gamma^{ij kl mn} C_i C_j) \dot{\gamma}_{kl} \dot{\gamma}_{mnl} \\ & - \frac{1}{2} e^{2\psi} \Gamma^{ij kl} C_i C_j \dot{C}_k \dot{C}_l - \frac{1}{2} (3e^{-2\psi} + C_i C^i) \dot{\psi}^2. \end{aligned}$$

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Leading order in the $1/c$ expansion:

$$L_{\text{LO}} = L_0 = R + \frac{1}{4} e^{2\psi} C_{ij} C^{ij} - \frac{1}{2} \partial_i \psi \partial^i \psi$$

- no time derivatives
- stationary sector of GR
- $1/c$ expansion is a 'post-stationary' expansion

The $1/c$ expansion of GR

3+1 formulation of the $1/c$ expansion

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Higher order in the $1/c$ expansion:

$$\psi = \sum_{n=0}^{\infty} \psi^{(n)} c^{-n} \quad C_i = \sum_{n=0}^{\infty} C_i^{(n)} c^{-n} \quad \gamma_{ij} = \sum_{n=0}^{\infty} \gamma_{ij}^{(n)} c^{-n}$$

\Rightarrow eoms take the form

$$\mathbb{D}^2 \Phi^{(n)} = \mathbb{S} \left[\Phi^{(n-1)}, \dots, \Phi^{(0)}, \partial_t \Phi^{(n-1)}, \dots, \partial_t \Phi^{(0)}, \partial_t^2 \Phi^{(n-2)}, \dots, \partial_t^2 \Phi^{(0)} \right]$$

The $1/c$ expansion of GR

3+1 formulation of the $1/c$ expansion

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	ψ	C_i	γ_{ij}	ψ	C_i	γ_{ij}	ψ	C_i	γ_{ij}
c^0	ψ	C_i	γ_{ij}	ψ	0	γ_{ij}	0	0	δ_{ij}
c^{-1}	χ	B_i	α_{ij}	0	B_i	0	0	0	0
c^{-2}	ϕ	A_i	β_{ij}	ϕ	0	β_{ij}	$-2U$	0	0
c^{-3}	v	Z_i	ϖ_{ij}	0	Z_i	0	0	$4U_i$	0
c^{-4}	τ	Y_i	ϵ_{ij}	τ	0	ϵ_{ij}	-2Ψ	0	

$1/c$

$1/c^2$

Post-Newtonian

Post-stationary

Post-Static

The $1/c$ expansion of GR

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What determines the time dependence?

A dynamic dS black hole

Static SdS metric

$$ds^2 = -F dt^2 + F^{-1} dr^2 + r^2 d\Omega_2^2, \quad F = 1 - \frac{2m}{r} - \frac{\Lambda r^2}{3}$$

Solution to

$$L = \sqrt{-g} \left(R - \frac{1}{2} \partial_\mu \Phi \partial^\mu \Phi - V(\Phi) \right)$$

with

$$\Phi = \bar{\Phi} \longleftarrow \text{cst such that } V'(\bar{\Phi}) = 0$$

$$\Lambda = \frac{V(\bar{\Phi})}{2}$$

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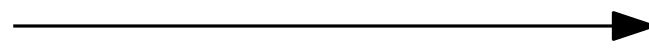
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(Gregory, Kastor, Traschen)

slow time dependence

Parameters: $m, \bar{\Phi}$



At leading order
 $m(t), \bar{\Phi}(t)$

+ lower order corrections

A dynamic dS black hole

A precise quasi-stationary expansion

- Generic spherically symmetric ansatz

$$ds^2 = -F A^2 du^2 + 2H A du dr + \frac{1 - H^2}{F} dr^2 + r^2 d\Omega_2^2$$

$$F = F(u, r), \quad H = H(u, r), \quad A = A(u, r), \quad \Phi = \Phi(u)$$

A dynamic dS black hole

A precise quasi-stationary expansion

- Generic spherically symmetric ansatz

$$ds^2 = -F A^2 du^2 + 2H A du dr + \frac{1 - H^2}{F} dr^2 + r^2 d\Omega_2^2$$

- Introduce a small parameter ϵ via slow time $\tau = \epsilon u$

$$F(u, r) = f(\epsilon u, r), \quad H(u, r) = \eta(\epsilon u, r), \quad A(u, r) = a(\epsilon u, r)$$

$$\sqrt{\epsilon} \Phi(u) = \varphi(\epsilon u), \quad V(\Phi) = v(\sqrt{\epsilon} \Phi)$$

A dynamic dS black hole

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$$\sqrt{\epsilon} \Phi(u) = \varphi(\epsilon u), \quad V(\Phi) = v(\sqrt{\epsilon} \Phi)$$

\Rightarrow Einstein equations + scalar eom reduce to

$$\zeta \partial_r a^2 = \epsilon \frac{d}{d\tau} \frac{a^2 \zeta^2 - 1}{f} \quad \partial_r \left(r \left(f - 1 + \frac{v}{6} r^2 \right) \right) = \epsilon \frac{a^2 \zeta^2 - 1}{a^2 f} r$$

$$\left(-\eta/a = \zeta = \frac{2 \partial_\tau f}{r \dot{\varphi}^2} \right)$$

A dynamic dS black hole

A precise quasi-stationary expansion

- Generic spherically symmetric ansatz

$$ds^2 = -FA^2 du^2 + 2HAdudr + \frac{1-H^2}{F} dr^2 + r^2 d\Omega_2^2$$

- Introduce a small parameter ϵ via slow time $\tau = \epsilon u$

$$F(u, r) = f(\epsilon u, r), \quad H(u, r) = \eta(\epsilon u, r), \quad A(u, r) = a(\epsilon u, r)$$

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$$\Rightarrow \text{solve perturbatively: } a = \sum_{n=0}^{\infty} a_n \epsilon^n \quad f = \sum_{n=0}^{\infty} f_n \epsilon^n$$

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\Rightarrow solve perturbatively: $a = \sum_{n=0}^{\infty} a_n \epsilon^n$ $f = \sum_{n=0}^{\infty} f_n \epsilon^n$

\hookrightarrow $\epsilon = 1/c \Leftrightarrow 1/c$ expansion!

A dynamic dS black hole

At leading order:

$$\partial_r a_0^2 = 0 \quad \partial_r \left(r \left(f_0 - 1 + \frac{v}{6} r^2 \right) \right) = 0$$

$$\Rightarrow \quad a_0 = 1 \quad f_0 = 1 - \frac{2m(\tau)}{r} - \frac{v(\varphi(\tau))}{6} r^2$$

Observe: Einstein equations leave $m(\tau)$ and $\varphi(\tau)$ undetermined!

A dynamic dS black hole

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Resolution: (Gregory, Kastor, Traschen)

boundary condition on horizons

$$\varphi \text{ purely ingoing} \quad \Leftrightarrow \quad \begin{cases} \dot{m} &= \beta[m, v(\varphi)] \dot{\varphi}^2 \\ \dot{\varphi} &= -\frac{v'(\varphi)}{3\gamma[m, v(\varphi)]} \end{cases}$$

Summary

The quasi-stationary regime of GR

- remains largely unexplored
- is highly tractable
- reveals elegant geometric structures

Interesting open issues

- connection to asymptotic symmetries and soft modes
- how is time dependence determined in $1/c$?
- applications